

# Semantics

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# Last time

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- Mathematical basis:
  - Transition systems
  - Partially ordered sets (posets), Complete partial orders (CPOs), Complete lattices
  - Galois connections
  - Fixed points
- Abstract interpretation basics:
  - Reachable states collecting semantics
  - Galois-connection based abstract interpretation
  - The alternative widening/narrowing framework
- OCaml intro

# Semantics

# Semantics according to Merriam-Webster

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Main Entry: se·man·tics

Pronunciation: si-'man-tiks

Function: noun plural but singular or plural in construction

Date: 1893

1. *the study of meanings*: a : the historical and psychological study and the classification of changes in the signification of words or forms viewed as factors in linguistic development b (1) : semiotic (2) : a branch of semiotic dealing with the relations between signs and what they refer to and including theories of denotation, extension, naming, and truth
2. general semantics
3. a : *the meaning or relationship of meanings* of a sign or set of signs; especially : connotative meaning b : the language used (as in advertising or political propaganda) to achieve a desired effect on an audience especially through the use of words with novel or dual meanings

# Semantics in Computer Science

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Semantics is concerned with constructing formal models or specifications of systems. Examples of such systems include: Java, ML, JavaScript, . . . , JVM, x86, . . .

A model in itself is useful

- to understand features (scope, exceptions, continuations,...)
- to prove equivalence of programs
- to prove program transformations correct
- to prove properties (e.g., type safety)

In this course semantics will be the starting point for abstraction/approximation.

# Many forms of semantics

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- Denotational semantics
- Operational semantics
  - abstract machines/transition systems
  - structured operational semantics
  - big-step/natural/relational semantics
- Reduction semantics
- Axiomatic semantics/Hoare logic
- Game semantics

Hence enough for a separate course.

# Semantics in this course

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In this course we will focus on abstract machines, i.e., transition systems. These models are *operational* in that they describe the inner workings of an idealized machine.

Today we'll study semantics of four different languages:

- of three counter machine programs
- of CPS programs
- of IMP programs
- of bytecode programs

Throughout we take the AST view: We assume that all ambiguities have been resolved, and we will work with (and reason about) programs as abstract syntax trees. 7 / 45

Warm-up: The three counter machine



# Plotkin's three counter machine (1/2)

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There are 3 variables (or registers):

$var \in Var = \{x, y, z\}$  (variables)

$Inst ::= inc\ var$  (instructions)  
|  $dec\ var$   
|  $zero\ var\ m\ else\ n$   
|  $stop$

$P = Inst^*$  (programs)

$pc \in PC = \mathbb{N}$  (program counter)

$States = PC \times \mathbb{N}_0 \times \mathbb{N}_0 \times \mathbb{N}_0$  (states)

Initial state:  $\langle 1, i, 0, 0 \rangle$  (for program  $P$  with input  $i$ )

Final state:  $\langle pc, 0, yv, 0 \rangle$   
(with  $yv$  being the result and where  $P_{pc} = stop$ ) 9 / 45

# Plotkin's three counter machine (1/2)

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$$\begin{aligned} Inst ::= & \text{inc } var && (\text{instructions}) \\ & | \text{dec } var \\ & | \text{zero } var \ m \ \text{else } n \\ & | \text{stop} \end{aligned}$$

$$P = Inst^* \quad (\text{programs})$$

$$pc \in PC = \mathbb{N} \quad (\text{program counter})$$

$$States = PC \times \mathbb{N}_0 \times \mathbb{N}_0 \times \mathbb{N}_0 \quad (\text{states})$$

Initial states:  $\{\langle 1, i, 0, 0 \rangle \mid i \in \mathbb{N}_0\}$  (for program  $P$  with input  $i$ )

Final states:  $\{\langle pc, 0, yv, 0 \rangle \mid pc \in PC \wedge yv \in \mathbb{N}_0 \wedge P_{pc} = \text{stop}\}$   
(with  $yv$  being the result) 9 / 45

# Plotkin's three counter machine (2/2)

Transition relation:

$$\begin{array}{ll} \langle pc, xv, yv, zv \rangle \longrightarrow \langle pc + 1, xv + 1, yv, zv \rangle & \text{if } P_{pc} = \text{inc } x \\ - \longrightarrow \langle pc + 1, xv, yv + 1, zv \rangle & \text{if } P_{pc} = \text{inc } y \\ - \longrightarrow \langle pc + 1, xv, yv, zv + 1 \rangle & \text{if } P_{pc} = \text{inc } z \\ \\ \langle pc, xv, yv, zv \rangle \longrightarrow \langle pc + 1, xv - 1, yv, zv \rangle & \text{if } P_{pc} = \text{dec } x \wedge xv > 0 \\ - \longrightarrow \langle pc + 1, xv, yv - 1, zv \rangle & \text{if } P_{pc} = \text{dec } y \wedge yv > 0 \\ - \longrightarrow \langle pc + 1, xv, yv, zv - 1 \rangle & \text{if } P_{pc} = \text{dec } z \wedge zv > 0 \\ \\ \langle pc, xv, yv, zv \rangle \longrightarrow \langle pc', xv, yv, zv \rangle & \text{if } P_{pc} = \text{zero } x \text{ } pc' \text{ else } pc'' \wedge xv = 0 \\ - \longrightarrow \langle pc'', xv, yv, zv \rangle & \text{if } P_{pc} = \text{zero } x \text{ } pc' \text{ else } pc'' \wedge xv \neq 0 \\ \\ \langle pc, xv, yv, zv \rangle \longrightarrow \langle pc', xv, yv, zv \rangle & \text{if } P_{pc} = \text{zero } y \text{ } pc' \text{ else } pc'' \wedge yv = 0 \\ - \longrightarrow \langle pc'', xv, yv, zv \rangle & \text{if } P_{pc} = \text{zero } y \text{ } pc' \text{ else } pc'' \wedge yv \neq 0 \\ \\ \langle pc, xv, yv, zv \rangle \longrightarrow \langle pc', xv, yv, zv \rangle & \text{if } P_{pc} = \text{zero } z \text{ } pc' \text{ else } pc'' \wedge zv = 0 \\ - \longrightarrow \langle pc'', xv, yv, zv \rangle & \text{if } P_{pc} = \text{zero } z \text{ } pc' \text{ else } pc'' \wedge zv \neq 0 \end{array}$$

Note: there is no case for the `stop` instruction.

Also note: this version differs slightly from Plotkin's.

# Exercise

---

Compute the first five execution steps of the following program for input 1:

```
1  zero x 6 else 2
2  dec x
3  inc y
4  inc y
5  zero x 6 else 2
6  stop
```

# Exercise

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1  zero x 6 else 2
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4  inc y
5  zero x 6 else 2
6  stop
```

Bonus question: how can we encode unconditional jumps?

# CPS semantics

# Representing functional values

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In languages like JavaScript, Scheme, and ML functions are first class values. That means the result of evaluating:

$$((\lambda (x) (\lambda (y) (+ x y))) 3)$$

is a functional value  $(\lambda (y) (+ x y))$  in which  $x$  is bound to 3.

To represent such a value we could substitute all free occurrences of  $x$  with 3. Alternatively we can record substitutions in an *environment* and represent functional values as *lambda*  $\times$  *env*-pairs:

$$\langle (\lambda (y) (+ x y)), \bullet[x \mapsto 3] \rangle$$

Such a representation is called a *closure*. It is also the representation used by most Scheme and ML interpreters and compilers.

# From $\lambda$ -calculus to ANF

---

$e ::= x \mid (\lambda (x) e) \mid (e_0 e_1)$  (lambda calculus)

To make things easier for ourselves, we will bind the result of each intermediate computation to a name  $v$ .

$P \ni p ::= s$  (programs)

$T \ni t ::= x \mid v \mid (\lambda (x) s)$  (trivial expressions)

$C \ni s ::= t$  (serious expressions)

$\mid (\text{let } ((v t)) s)$

$\mid (t_0 t_1)$

$\mid (\text{let } ((v (t_0 t_1))) s)$

The grammar distinguishes *serious* expressions, (whose evaluation may diverge), from *trivial* expressions (whose evaluation will terminate).



# Encoding control stacks as continuations

---

As a second step we will pass around our own control stack, encoded as a lambda term.

Hence every function will accept an additional parameter, *the continuation*.

Just as a plain control-stack tells us what to do next, our encoded stack (*the continuation*), tells us what to do next.

Actually, we don't need to adhere to a stack-discipline, when we are implementing it ourselves (in the term).

Hence you can do funny stuff, like returning to the stack twice, not returning (i.e., jumping out of context), etc.

# Example: continuation passing style

---

Consider an example:

```
(let ((f (λ (x) x))
      ((f f) (λ (y) y))))
```

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Sequentialized and with all intermediate computations named:

```
(let ((f (λ (x) x)))  
      (let ((v (f f)))  
            (v (λ (y) y))))
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Sequentialized and with all intermediate computations named:

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      (let ((v (f f)))
          (v (λ (y) y))))
```

In continuation-passing style:

```
(λ (k0) (let ((f (λ (x k) (k x))))
           (f f (λ (v)
                 (v (λ (y k2) (k2 y)) k0))))))
```

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Sequentialized and with all intermediate computations named:

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```

In continuation-passing style:

```
(λ (k0) ((λ (f k1)  
          (f f (λ (v)  
                (v (λ (y k2) (k2 y)) k1))))  
        (λ (x k) (k x)) k0)))
```

# CPS syntax

---

Formally, our grammar of CPS expressions is:

$p ::= (\lambda (k) e)$	(CPS programs)
$SExp \ni e ::= (t_0 t_1 c) \mid (c t)$	(serious expr)
$TExp \ni t ::= x \mid v \mid (\lambda (x k) e)$	(trivial expr)
$CExp \ni c ::= (\lambda (v) e) \mid k$	(continuation expr)

here expressed in Scheme syntax

# Expressiveness

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The language is Turing-complete, in that it is sufficient to express a CPS-version of the  $\Omega$ -combinator

$$((\lambda (x) (x x)) (\lambda (y) (y y))) :$$
$$(\lambda (k_0) ((\lambda (x k_1) (x x k_1)) (\lambda (y k_2) (y y k_2)) k_0))$$

The CPS language represents the Church-side of the Church-Turing thesis.

One can thus Church-encode numbers:

$$c_0 = \lambda s. \lambda z. z \quad \rightarrow (\lambda (s k_0) (k_0 (\lambda (z k_1) (k_1 z))))$$
$$c_1 = \lambda s. \lambda z. s z \quad \rightarrow (\lambda (s k_0) (k_0 (\lambda (z k_1) (s z (\lambda (v) (k_1 v))))))$$
$$c_2 = \lambda s. \lambda z. s(s z) \quad \rightarrow \dots$$

# CPS transforming ANF programs

---

Once programs are sequentialized and name all intermediate results, transforming into CPS is straightforward.

We formulate one transformation function for programs  $\mathcal{C}$ , for trivial terms  $\mathcal{V}$ , and for serious terms  $\mathcal{F}$ :

$$\begin{aligned} \mathcal{C} &: P \rightarrow CProg \\ \mathcal{C}[p] &= (\lambda (k_p) \mathcal{F}_{k_p}[p]) \\ &\text{where } k_p \text{ is fresh} \end{aligned}$$

$$\begin{aligned} \mathcal{V} &: T \rightarrow TExp \\ \mathcal{V}[x] &= x \\ \mathcal{V}[(\lambda (x) s)] &= (\lambda (x k_s) \mathcal{F}_{k_s}[s]) \\ &\text{where } k_s \text{ is fresh} \end{aligned}$$

$$\begin{aligned} \mathcal{F} &: K \rightarrow C \rightarrow SExp \\ \mathcal{F}_k[t] &= (k \mathcal{V}[t]) \\ \mathcal{F}_k[(\text{let } ((x t)) s)] &= ((\lambda (x) \mathcal{F}_k[s]) \mathcal{V}[t]) \\ \mathcal{F}_k[(t_0 t_1)] &= (\mathcal{V}[t_0] \mathcal{V}[t_1] k) \\ \mathcal{F}_k[(\text{let } ((x (t_0 t_1))) s)] &= (\mathcal{V}[t_0] \mathcal{V}[t_1] (\lambda (x) \mathcal{F}_k[s])) \end{aligned}$$



# The CE abstract machine

---

Values and environments:

$$Val \ni w ::= [(\lambda (x\ k) e), r] \mid [(\lambda (v) e), r] \mid \mathbf{stop}$$
$$Env \ni r ::= \bullet \mid r[x \mapsto w]$$

# The CE abstract machine

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$$Env \ni r ::= \bullet \mid r[x \mapsto w]$$

Two helper functions:

$$\mu_t : TExp \times Env \rightarrow Val$$

$$\mu_t(x, r) = r(x)$$

$$\mu_t(v, r) = r(v)$$

$$\mu_t((\lambda (x\ k) e), r) = [(\lambda (x\ k) e), r]$$

$$\mu_c : CExp \times Env \rightarrow Val$$

$$\mu_c(k, r) = r(k)$$

$$\mu_c((\lambda (v) e), r) = [(\lambda (v) e), r]$$

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$$\mu_c(k, r) = r(k)$$

$$\mu_c((\lambda (v) e), r) = [(\lambda (v) e), r]$$

Transition relation (over  $SExp \times Env$ ):

$$\text{if } [(\lambda (x k) e), r'] = \mu_t(t_0, r)$$

$$\langle (t_0 t_1 c), r \rangle \longrightarrow \langle e, r'[x \mapsto w][k \mapsto w_c] \rangle$$

$$w = \mu_t(t_1, r)$$

$$w_c = \mu_c(c, r)$$

$$\langle (c t), r \rangle \longrightarrow \langle e, r'[v \mapsto w] \rangle$$

$$\text{if } [(\lambda (v) e), r'] = \mu_c(c, r)$$

$$w = \mu_t(t, r)$$

Initial state:

$$\langle e, \bullet[k \mapsto [(\lambda (v_r) (k_r v_r)), \bullet[k_r \mapsto \text{stop}]]] \rangle \text{ for program } (\lambda (k) e)$$

# Exercise

---

Trace the first four steps of the CE-machine on the  $\Omega$ -combinator in CPS:

$$(\lambda (k_0) ( (\lambda (x k_1) (x x k_1)) (\lambda (y k_2) (y y k_2)) k_0 ) )$$

# To CPS transform or not to CPS transform

---

Note: we don't need to CPS transform terms to give an abstract machine semantics.

Flanagan-al:PLDI93 (optional reading) provides alternative abstract machines for non-CPS-transformed terms.

From Olivier's TFP course some of you know how to construct even more by yourselves.

# IMP semantics

# IMP programs

---

We'll study a simple imperative language IMP, composed of statements, arithmetic expressions, and boolean expressions:

$s \ni Stmt ::= x = e$	$e \ni AExp ::= n$
skip	?
if <i>test</i> then <i>s</i> else <i>s</i>	<i>x</i>
while <i>test</i> do <i>s</i>	<i>e op e</i>
<i>s</i> ; <i>s</i>	where $op \in \{+, -, *, \dots\}$

$test \ni BExp ::= e \text{ comp } e$	where $comp \in \{=, <>, <, \dots\}$
<i>test</i> and <i>test</i>	
<i>test</i> or <i>test</i>	

Note: because of ?, programs are non-deterministic.

# Imperative programs as flow graphs

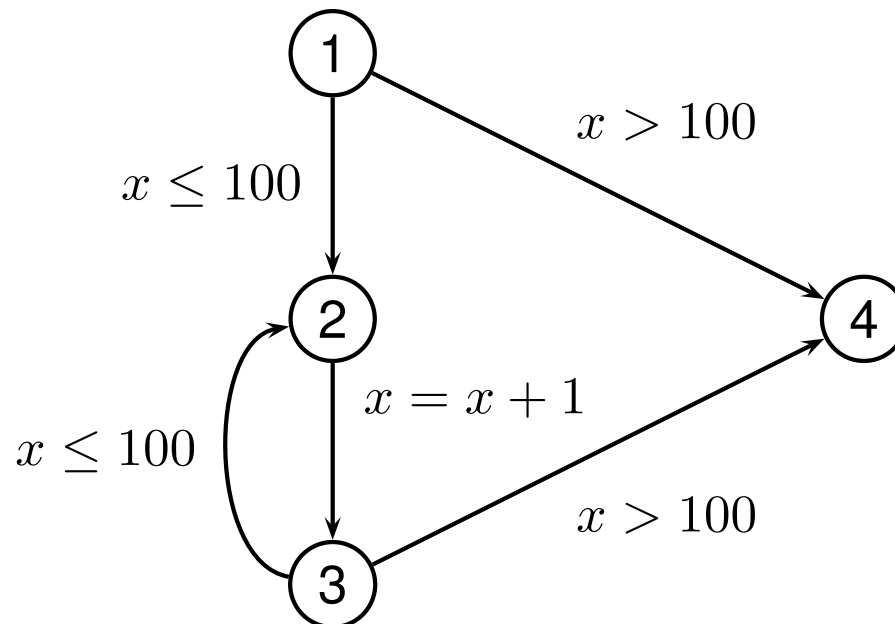
---

Rather than giving a direct semantics, we will represent simple imperative programs using their *flow graph* (or *flow chart*).

We associate program actions (tests, assignments, etc.) to the edges of the graph (instead of associating them to the nodes of the graph).

Example:

```
while x ≤ 100 {  
    x = x + 1;  
}
```





# Flow graphs, formally

---

Formally, a program graph is a quadruple  $\langle V, v_{entry}, v_{exit}, E \rangle$ , where

- $V$  is a finite set of vertices
- $E \subseteq V \times V$  is a finite set of edges
- $v_{entry} \in V$  is a distinct entry vertex (in-degree 0)
- $v_{exit} \in V$  is a distinct exit vertex (out-degree 0)

Every vertex lies on a path from  $v_{entry}$  to  $v_{exit}$ .

# Imperative programs as flow graphs, formally

---

Instructions are divided into assignments and tests:

$$I ::= x = e \\ \quad | \text{ assert } test$$

A program is a triple  $\langle G, U, L \rangle$ , where

- the program graph  $G$
- the universe  $U$  of variables,  $(x, y \in U)$
- the labelling function  $L \in (E \rightarrow I)$  associating an instruction to each edge

# Semantics of arithmetic expressions and tests

---

A store remembers the program state:  $\rho \ni Store = U \rightarrow \mathbb{Z}$

$$\mathcal{A} : AExp \rightarrow Store \rightarrow \wp(\mathbb{Z})$$

$$\mathcal{A} \llbracket n \rrbracket \rho = \{n\}$$

$$\mathcal{A} \llbracket ? \rrbracket \rho = \mathbb{Z}$$

$$\mathcal{A} \llbracket \mathbf{x} \rrbracket \rho = \{\rho(\mathbf{x})\}$$

$$\mathcal{A} \llbracket e \ op \ e' \rrbracket \rho = \{n \ op \ n' \mid n \in \mathcal{A} \llbracket e \rrbracket \rho, n' \in \mathcal{A} \llbracket e' \rrbracket \rho\} \quad \text{where } op \in \{+, -, *, \dots\}$$

Note: by computing over  $\mathbb{Z}$  we are ignoring overflow.

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$$\mathcal{A} \llbracket e \text{ op } e' \rrbracket \rho = \{n \text{ op } n' \mid n \in \mathcal{A} \llbracket e \rrbracket \rho, n' \in \mathcal{A} \llbracket e' \rrbracket \rho\} \quad \text{where } op \in \{+, -, *, \dots\}$$

**Note:** by computing over  $\mathbb{Z}$  we are ignoring overflow.

$$\mathcal{B} : BExp \rightarrow Store \rightarrow \wp(\mathbb{B}) \quad \text{where } \mathbb{B} = \{true, false\}$$

$$\mathcal{B} \llbracket e \text{ comp } e' \rrbracket \rho = \begin{aligned} & \{true \mid n \in \mathcal{A} \llbracket e \rrbracket \rho \wedge n' \in \mathcal{A} \llbracket e' \rrbracket \rho \wedge n \text{ comp } n'\} \\ & \cup \{false \mid n \in \mathcal{A} \llbracket e \rrbracket \rho \wedge n' \in \mathcal{A} \llbracket e' \rrbracket \rho \wedge \neg(n \text{ comp } n')\} \end{aligned}$$

$$\mathcal{B} \llbracket test \text{ and } test' \rrbracket \rho = \{b \wedge b' \mid b \in \mathcal{B} \llbracket test \rrbracket \rho \wedge b' \in \mathcal{B} \llbracket test' \rrbracket \rho\}$$

$$\mathcal{B} \llbracket test \text{ or } test' \rrbracket \rho = \{b \vee b' \mid b \in \mathcal{B} \llbracket test \rrbracket \rho \wedge b' \in \mathcal{B} \llbracket test' \rrbracket \rho\}$$

# IMP program execution as a transition system

---

States are pairs:

$$\text{State} = V \times \text{Store}$$

There is one case per instruction:

$$\langle v, \rho \rangle \rightarrow \langle v', \rho[\mathbf{x} \mapsto n] \rangle \quad \text{if} \quad \langle v, v' \rangle \in E \wedge \\ L(\langle v, v' \rangle) = (\mathbf{x} = e) \wedge \\ n \in \mathcal{A} \llbracket e \rrbracket \rho$$

$$\langle v, \rho \rangle \rightarrow \langle v', \rho \rangle \quad \text{if} \quad \langle v, v' \rangle \in E \wedge \\ L(\langle v, v' \rangle) = (\text{assert } test) \wedge \\ true \in \mathcal{B} \llbracket test \rrbracket \rho$$

Initial state:  $\langle v_{entry}, \rho \rangle$  (for initial store  $\rho$ )

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$$State = V \times Store$$

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Initial states:  $\{ \langle v_{entry}, \rho \rangle \mid \rho \in Store \}$  (for initial store  $\rho$ )

# Bytecode semantics

# Scope, mutation, and semantics

---

The CPS semantics tells us how to model binding and lexical scope, namely with environments.

The flow-graph semantics tells us how to model mutation, namely with a global store.

The bytecode semantics can express both — in addition to heap-allocated objects. It is hence a bit more complex.



# A JVM-like instruction set

---

$$\begin{aligned} Inst ::= & \text{nop} & | & \text{numop } op & | & \text{new } cl \\ & | & \text{push } c & | & \text{load } i & | & \text{putfield } f \\ & | & \text{pop} & | & \text{store } i & | & \text{getfield } f \\ & | & \text{dup} & | & \text{ifeq } pc & | & \text{invokevirtual } M \\ & | & \text{swap} & | & \text{goto } pc & | & \text{return} \end{aligned}$$

where  $op \in \{\text{add, sub, mul, div, rem, and, or, \dots}\}$

Numeric operations are collected in one bytecode.

$$pc \ni Address = \mathbb{N}$$
$$m \ni Method = MethodId \times (Address \rightarrow Inst)$$
$$Field = FieldName$$
$$c \ni Class = ClassName \times Class_{\perp} \times \wp(Field) \times \wp(Method)$$
$$P \ni Program = \wp(Class)$$

# Virtual machine domains

---

$loc \ni Locations$  (some countable number of locations)

$v \ni Value = n \mid loc \mid null$

$s \ni OperandStack = Value^*$

$l \ni LocalVar = [Value_{\perp}]$

$Frame = Method \times Address \times LocalVar \times OperandStack$

$sf \ni CallStack = Frame^*$

$o \ni Object = Class \times (FieldName \rightarrow Value)$

$h \ni Heap = Locations \rightarrow Object_{\perp}$

$State = Heap \times CallStack$

We now define a number of shorthands and helper functions:

$className(c) = \pi_1(c)$        $methodName(m) = \pi_1(m)$        $instAt_P(m, pc) = \pi_2(m)(pc)$

$methods(c) = \pi_4(c)$        $class(o) = \pi_1(o)$        $fieldValue(o, f) = \pi_2(o)(f)$

$newObject(h, c) = \langle h[loc \mapsto \langle c, \bullet \rangle], loc \rangle$  **where**  $loc \notin Dom(h)$

$lookup(M, c) = \begin{cases} m & \text{if } m \in methods(c) \wedge methodName(m) = M \\ lookup(M, \pi_2(c)) & \text{if } \pi_2(c) \neq \perp \wedge \langle M, \pi_2(c) \rangle \in Dom(lookup) \end{cases}$

# Byte code execution (1/3)

---

$$instAt_P(m, pc) = \mathbf{nop}$$

$$\frac{}{\langle h, (m, pc, l, s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, s) :: sf \rangle}$$

$$instAt_P(m, pc) = \mathbf{push\ c}$$

$$\frac{}{\langle h, (m, pc, l, s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, c :: s) :: sf \rangle}$$

$$instAt_P(m, pc) = \mathbf{pop}$$

$$\frac{}{\langle h, (m, pc, l, v :: s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, s) :: sf \rangle}$$

$$instAt_P(m, pc) = \mathbf{dup}$$

$$\frac{}{\langle h, (m, pc, l, v :: s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, v :: v :: s) :: sf \rangle}$$

$$instAt_P(m, pc) = \mathbf{swap}$$

$$\frac{}{\langle h, (m, pc, l, v_1 :: v_2 :: s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, v_2 :: v_1 :: s) :: sf \rangle}$$

$$instAt_P(m, pc) = \mathbf{numop\ op}$$

$$\frac{}{\langle h, (m, pc, l, n_1 :: n_2 :: s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, \llbracket op \rrbracket(n_1, n_2) :: s) :: sf \rangle}$$

# Byte code execution (2/3)

---

$$\frac{\text{instAt}_P(m, pc) = \text{load } i}{\langle h, (m, pc, l, s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, l(i) :: s) :: sf \rangle}$$

$$\frac{\text{instAt}_P(m, pc) = \text{store } i}{\langle h, (m, pc, l, v :: s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l[i \mapsto v], s) :: sf \rangle}$$

$$\frac{\text{instAt}_P(m, pc) = \text{ifeq } pc' \quad n = 0}{\langle h, (m, pc, l, n :: s) :: sf \rangle \rightarrow \langle h, (m, pc', l, s) :: sf \rangle}$$

$$\frac{\text{instAt}_P(m, pc) = \text{ifeq } pc' \quad n \neq 0}{\langle h, (m, pc, l, n :: s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, s) :: sf \rangle}$$

$$\frac{\text{instAt}_P(m, pc) = \text{goto } pc'}{\langle h, (m, pc, l, s) :: sf \rangle \rightarrow \langle h, (m, pc', l, s) :: sf \rangle}$$

$$\frac{\text{instAt}_P(m, pc) = \text{new } cl \quad \exists c \in \text{classes}(P) : \text{className}(c) = cl \quad \langle h', loc \rangle = \text{newObject}(h, c)}{\langle h, (m, pc, l, s) :: sf \rangle \rightarrow \langle h', (m, pc + 1, l, loc :: s) :: sf \rangle}$$

# Byte code execution (3/3)

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$$\frac{\text{instAt}_P(m, pc) = \text{putfield } f \quad h(\text{loc}) = o \quad o' = \langle \text{class}(o), \pi_2(o)[f \mapsto v] \rangle}{\langle h, (m, pc, l, v :: \text{loc} :: s) :: sf \rangle \rightarrow \langle h[\text{loc} \mapsto o'], (m, pc + 1, l, s) :: sf \rangle}$$

$$\frac{\text{instAt}_P(m, pc) = \text{getfield } f \quad h(\text{loc}) = o}{\langle h, (m, pc, l, \text{loc} :: s) :: sf \rangle \rightarrow \langle h, (m, pc + 1, l, \text{fieldValue}(o, f) :: s) :: sf \rangle}$$

$$\frac{\begin{array}{l} \text{instAt}_P(m, pc) = \text{invokevirtual } M \\ h(\text{loc}) = o \quad m' = \text{lookup}(M, \text{class}(o)) \end{array}}{\langle h, (m, pc, l, \text{loc} :: \vec{v} :: s) :: sf \rangle \rightarrow \langle h, (m', 1, \text{loc} \cdot \vec{v}, \epsilon) :: (m, pc, l, s) :: sf \rangle}$$

$$\frac{\text{instAt}_P(m, pc) = \text{return}}{\langle h, (m, pc, l, v :: s) :: (m', pc', l', s') :: sf \rangle \rightarrow \langle h, (m', pc' + 1, l', v :: s') :: sf \rangle}$$

Initial state:

$$\langle \bullet, (\text{lookup}(\text{main}, c), 1, \epsilon, \epsilon) :: \epsilon \rangle$$

for program  $P$  and class  $c$ .

# Collecting semantics, revisited

# Collecting semantics, revisited (1/3)

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We formulate the collecting semantics in terms of sets because they describe properties, e.g.,

- the set  $\{1, 3, 5, \dots\}$  describes the property *odd*
- the set  $\{2, 4, 6, \dots\}$  describes the property *even*
- the singleton set  $\{42\}$  describes a constant property
- the set  $\{4, 5, 6, 7, 8, 9, 10\}$  describes an interval property  $[4; 10]$
- ...

In this sense, the collecting semantics is the strongest property expressed as a (generally uncomputable) fixed point.

# Collecting semantics, revisited (2/3)

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The collecting semantics forms a logic.

In our case the reachable states collecting semantics over  $\langle \wp(S); \subseteq, \emptyset, S, \cup, \cap \rangle$  can be understood as follows.

- $\subseteq$  is implication
- $\emptyset$  is false
- $S$  is true
- $\cup$  is disjunction
- $\cap$  is conjunction



# Collecting semantics, revisited (3/3)

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A post-fixed point  $\Sigma'$  of  $T(\Sigma) = I \cup \{s' \mid \exists s \in \Sigma : s \rightarrow s'\}$  satisfies:

- $I \subseteq \Sigma' \sim$  “The initial state satisfies  $\Sigma'$ ”
- $\{s' \mid \exists s \in \Sigma' : s \rightarrow s'\} \subseteq \Sigma'$   
 $\sim$  “ $\Sigma'$  is preserved across transitions”

Thus  $\Sigma'$  is an *invariant*.

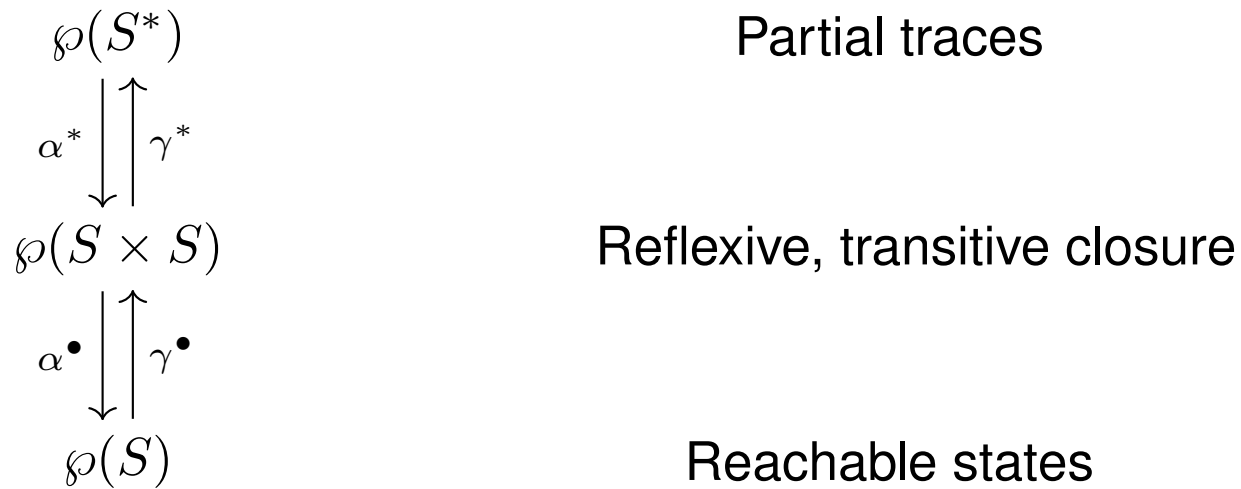
A fixed point computation describes the iterative search for an invariant in this logic.

Note: any post-fixed point of  $T$  is a valid invariant (but some are more interesting than others...)

# Stronger properties, stronger collecting semantics

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There is a hierarchy of increasingly powerful collecting semantics:



# Stronger properties, stronger collecting semantics

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There is a hierarchy of increasingly powerful collecting semantics:

$$\begin{array}{ccc} \wp(S^*) & \lambda X. \{s \mid s \in S\} \cup \{\sigma s s' \mid \sigma s \in X \wedge s \rightarrow s'\} \\ \alpha^* \downarrow \uparrow \gamma^* & \\ \wp(S \times S) & \lambda Y. \{\langle s, s \rangle \mid s \in S\} \cup \{\langle s, s'' \rangle \mid \exists s' : \langle s, s' \rangle \in Y \wedge s' \rightarrow s''\} \\ \alpha^\bullet \downarrow \uparrow \gamma^\bullet & \\ \wp(S) & \lambda Z. I \cup \{s' \mid \exists s \in Z : s \rightarrow s'\} \end{array}$$

Each can be expressed as a least fixed point

# Example: collecting semantics for the CE

---

Reachable states:  $T(\Sigma) = I \cup \{s' \mid \exists s \in \Sigma : s \rightarrow s'\}$

Recall transitions:

$$\langle (t_0 t_1 c), r \rangle \longrightarrow \langle e, r'[x \mapsto w][k \mapsto w_c] \rangle$$

$$\text{if } [(\lambda (x k) e), r'] = \mu_t(t_0, r)$$

$$w = \mu_t(t_1, r)$$

$$w_c = \mu_c(c, r)$$

$$\langle (c t), r \rangle \longrightarrow \langle e, r'[v \mapsto w] \rangle$$

$$\text{if } [(\lambda (v) e), r'] = \mu_c(c, r)$$

$$w = \mu_t(t, r)$$

# Example: collecting semantics for the CE

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$$\langle (c t), r \rangle \longrightarrow \langle e, r'[v \mapsto w] \rangle \quad \begin{array}{l} \text{if } [(\lambda (v) e), r'] = \mu_c(c, r) \\ w = \mu_t(t, r) \end{array}$$

Direct definition (for a given program  $(\lambda (k) e)$ ):

$$\begin{aligned} T(S) = & I_{(\lambda (k) e)} \\ & \cup \{ \langle e', r'[x \mapsto w][k' \mapsto w_c] \rangle \mid \exists \langle (t_0 t_1 c), r \rangle \in S : \\ & \quad [(\lambda (x k') e'), r'] \in \mu_t^{\wp}(t_0, \{r\}) \\ & \quad \wedge w \in \mu_t^{\wp}(t_1, \{r\}) \\ & \quad \wedge w_c \in \mu_c^{\wp}(c, \{r\}) \} \\ & \cup \{ \langle e', r'[v \mapsto w] \rangle \mid \exists \langle (c t), r \rangle \in S : \\ & \quad [(\lambda (v) e'), r'] \in \mu_c^{\wp}(c, \{r\}) \\ & \quad \wedge w \in \mu_t^{\wp}(t, \{r\}) \} \end{aligned}$$

# Example cont.: properties of helper functions

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Recall helper functions:

$$\mu_t : TExp \times Env \rightarrow Val$$

$$\mu_t(x, r) = r(x)$$

$$\mu_t(v, r) = r(v)$$

$$\mu_t((\lambda (x k) e), r) = [(\lambda (x k) e), r]$$

$$\mu_c : CExp \times Env \rightarrow Val$$

$$\mu_c(k, r) = r(k)$$

$$\mu_c((\lambda (v) e), r) = [(\lambda (v) e), r]$$

Collecting helper functions:

$$\mu_t^\wp : TExp \times \wp(Env) \rightarrow \wp(Val)$$

$$\mu_t^\wp(x, E) = \{r(x) \mid r \in E\}$$

$$\mu_t^\wp(v, E) = \{r(v) \mid r \in E\}$$

$$\mu_t^\wp((\lambda (x k) e), E) = \{[(\lambda (x k) e), r] \mid r \in E\}$$

$$\mu_c^\wp : CExp \times \wp(Env) \rightarrow \wp(Val)$$

$$\mu_c^\wp(k, E) = \{r(k) \mid r \in E\}$$

$$\mu_c^\wp((\lambda (v) e), E) = \{[(\lambda (v) e), r] \mid r \in E\}$$

# Summary

# Summary

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We've seen four different abstract machine semantics:

- Plotkin's three counter machine
- the CE machine for CPS programs
- a flow-chart semantics for IMP programs
- a JVM-like semantics for bytecodes

Finally we took another look at collecting semantics.