
Constraint Programming: Theory and Practice

Topics:

Rational Tree Solver (RT)

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Rational Trees (RTs)

Possibly **infinite tree** which has a finite set of subtrees.

- No *occur-check* in early Prolog implementations for efficiency reasons, unification could go into an infinite loop
- In Prolog II, algorithm for properly handling the resulting infinite terms was introduced
- **Rational trees**: finite and infinite terms that are representable by finite trees

Example:

- Infinite tree $f(f(f(\dots)))$ only contains itself
- finite representation as directed (possibly cyclic) graph
- representation as equality constraint, e.g., $X=f(X)$

Constraint System RT

- Based on constraint system E (finite trees)
- Constraint theory CET without acyclicity axiom (occur-check)

Signature

- Infinitely many function symbols.
- Constraint symbols.
 - Nullary symbols $true, false$
 - Binary symbol for syntactic equality =

Domain

Herbrand universe with Herbrand interpretation

Constraint System *RT* (2)

Constraint theory

Reflexivity $\forall(\text{true} \rightarrow x=x)$

Symmetry $\forall(x=y \rightarrow y=x)$

Transitivity $\forall(x=y \wedge y=z \rightarrow x=z)$

Compatibility $\forall(x_1=y_1 \wedge \dots \wedge x_n=y_n \rightarrow f(x_1, \dots, x_n)=f(y_1, \dots, y_n))$

Decomposition $\forall(f(x_1, \dots, x_n)=f(y_1, \dots, y_n) \rightarrow x_1=y_1 \wedge \dots \wedge x_n=y_n)$

Contradiction
(*Clash*) $\forall(f(x_1, \dots, x_n)=g(y_1, \dots, y_m) \rightarrow \text{false})$ if $f \neq g$ or $n \neq m$

Allowed atomic constraints

$C ::= \text{true} \mid \text{false} \mid s=t$

(s, t : terms over Σ)

RT – Solved Normal Form

Conjunction of allowed constraints is **solved (in solved normal form)**:

- *false* or
- $X_1=t_1 \wedge \dots \wedge X_n=t_n$ ($n \geq 0$)
 - X_1, \dots, X_n pairwise distinct
 - X_i different to t_j if $i \leq j$

Examples:

- Not in solved normal form:
 $f(X, b)=f(a, Y)$, or $X=t \wedge X=s$, or $X=Y \wedge Y=X$
- In solved normal form: $X=Z \wedge Y=Z \wedge Z=t$
- Logically equivalent but syntactically different solved forms:
 $X=Y$ and $Y=X$
 $X=f(X)$ and $X=f(f(X))$

RT – Variable Elimination Constraint Solver

- `s@<t`: built-in total order on terms
 - `s`, `t` variables: given order
 - `s` variable, `t` function term
 - `s` is ordered before `t` function terms: size of `s` is less than size of `t`
(*size*: number of occurrences of function symbols)
- `var(X)`, `nonvar(X)`
- `same_functor(T1,T2)`: tests if `T1` and `T2` have the same function symbol and the same arity
- `args2list(T1,L1)`: `L1` is the list of arguments of the term `T1`

RT – Variable Elimination Constraint Solver (2)

reflexivity @ $X \text{ eq } X \iff \text{var}(X) \mid \text{true}.$

orientation @ $T \text{ eq } X \iff \text{var}(X), X @ < T \mid X \text{ eq } T.$

decomposition @ $T1 \text{ eq } T2 \iff \text{nonvar}(T1), \text{nonvar}(T2) \mid$
 $\text{same_functor}(T1, T2),$
 $\text{args2list}(T1, L1), \text{args2list}(T2, L2),$
 $\text{same_args}(L1, L2).$

confrontation @ $X \text{ eq } T1, X \text{ eq } T2 \iff \text{var}(X), X @ < T1, T1 @ = < T2 \mid$
 $X \text{ eq } T1, T1 \text{ eq } T2.$

$\text{same_args}([], []) \iff \text{true}.$

$\text{same_args}([T1 \mid L1], [T2 \mid L2]) \iff T1 \text{ eq } T2, \text{same_args}(L1, L2).$

RT Example – Equating two Terms

$$\begin{array}{l} \text{\(\(\rightarrow\)}_{\text{decomposition}} \text{\(\rightarrow\)}^* \\ \text{\(\rightarrow\)}_{\text{orientation}} \\ \text{\(\rightarrow\)}_{\text{decomposition}} \text{\(\rightarrow\)}^* \\ \text{\(\rightarrow\)}_{\text{orientation}} \\ \text{\(\rightarrow\)}_{\text{confrontation}} \\ \text{\(\rightarrow\)}_{\text{decomposition}} \text{\(\rightarrow\)}^* \\ \text{\(\rightarrow\)}_{\text{confrontation}} \\ \text{\(\rightarrow\)}_{\text{decomposition}} \text{\(\rightarrow\)}^* \end{array} \quad \begin{array}{l} \frac{\text{h(Y, f(a), g(X, a)) eq h(f(U), Y, g(h(Y), U))}}{\text{Y eq f(U), } \underline{\text{f(a) eq Y}}, \text{ g(X, a) eq g(h(Y), U)}} \\ \text{Y eq f(U), } \underline{\text{Y eq f(a)}}, \underline{\text{g(X, a) eq g(h(Y), U)}} \\ \text{Y eq f(U), } \underline{\text{Y eq f(a)}}, \underline{\text{X eq h(Y)}}, \underline{\text{a eq U}} \\ \underline{\text{Y eq f(U)}}, \underline{\text{Y eq f(a)}}, \underline{\text{X eq h(Y)}}, \underline{\text{U eq a}} \\ \text{Y eq f(U), } \underline{\text{f(U) eq f(a)}}, \underline{\text{X eq h(Y)}}, \underline{\text{U eq a}} \\ \text{Y eq f(U), } \underline{\text{U eq a}}, \underline{\text{X eq h(Y)}}, \underline{\text{U eq a}} \\ \text{Y eq f(U), } \underline{\text{U eq a}}, \underline{\text{X eq h(Y)}}, \underline{\text{a eq a}} \\ \text{Y eq f(U), } \underline{\text{U eq a}}, \underline{\text{X eq h(Y)}} \end{array}$$

RT Example – Equating two Terms (2)

$$\begin{array}{l} \vdash_{\text{confrontation}} \\ \vdash_{\text{decomposition}} \vdash^* \\ \vdash_{\text{confrontation}} \\ \vdash_{\text{decomposition}} \vdash^* \\ \vdash_{\text{reflexivity}} \end{array} \quad \begin{array}{l} \frac{X \text{ eq } f(X), X \text{ eq } f(f(X))}{X \text{ eq } f(X), f(X) \text{ eq } f(f(X))} \\ \frac{X \text{ eq } f(X), X \text{ eq } f(X)}{X \text{ eq } f(X), f(X) \text{ eq } f(X)} \\ \frac{X \text{ eq } f(X), X \text{ eq } X}{X \text{ eq } f(X)} \\ X \text{ eq } f(X) \end{array}$$